

Technical Information
This map was compiled from data acquired during an airborne electromagnetic survey carried out by CGG using a HELIMET™ Time Domain Electromagnetic (TDEM) system. The system was mounted on a Eurocopter AS350B3 helicopter (registration C-FRMA) and was carried out between April 17th and April 30th, 2015. The aircraft flight elevation was maintained at a steady 100 m. Aerial navigation used a 12-channel NovAtel dual frequency GPS. Post-flight differential corrections were subsequently applied to finalize flight path position. A vertically mounted video camera was used to record images of the ground. The radar height was recorded for times per second using a Sorenson and the barometric altitude was recorded ten times per second using a Barometric altimeter. The magnetic data were recorded 10 times per second using a Sorenson CS-2 cesium-vapor magnetometer.

Survey Area Parameters

Traverse line azimuth	45/225°
Traverse line spacing	250 m
Tie line azimuth	135/225°
Tie line spacing	1000 m
Aircraft nominal clearance	83 m
EM transmitter nominal clearance	35 m
Magnetic sensor nominal clearance	35 m
EM Receiver nominal clearance	63 m

Electromagnetics
The TDEM system operating at a base frequency of 30 Hz transmits a 4 ms time-varying signal from a two-turn, 708 m² horizontal loop mounted approximately 47.0 m below and 12.5 m behind the aircraft. The configuration provides a dipole moment of 1.84 x 10⁷ Am². The response of conductors in the subsurface is sampled 2048 times per half-cycle using a three axis (X, Y, and Z) electromagnetic receiver mounted to a platform approximately 26.6 m above and 12.4 m in front of the transmitter loop. The EM receiver records data in a continuous stream for each of the three components. A second reference field (GRF) defined by a mean GPS altitude (1973.60 m) and a fixed recording rate (60 Hz) is used to remove the diurnal magnetic field variations. The EM receiver magnetic data were recorded ten times per second using a Sorenson CS-2 cesium-vapor magnetometer. The magnetic data were recorded 10 times per second using a Sorenson CS-2 cesium-vapor magnetometer.

Electromagnetic System Specifications

Base frequency	30 Hz
Waveform	Half sine wave
Pulse width	4 ms
Transmitter Area	708 m ² (2 turns)
Transmitter Off time	12.5 ms
Transmitter Loop	30 m diameter
Transmitter Current	1350 A
Dipole moment (approximate)	1.84x10 ⁷ Am ² (45°/135°)
Windowed data sampling rate	10 Hz
Receiver	3-component induction coil (X, Y, Z)
Measured Response	Voltage (dBV)
Digital recording	All raw data channels (30 channels)
1 st off-time channel	Channel 5 at -4.160 ms after pulse turn on
Tr-A-R Configuration	Towed transmitter below receiver

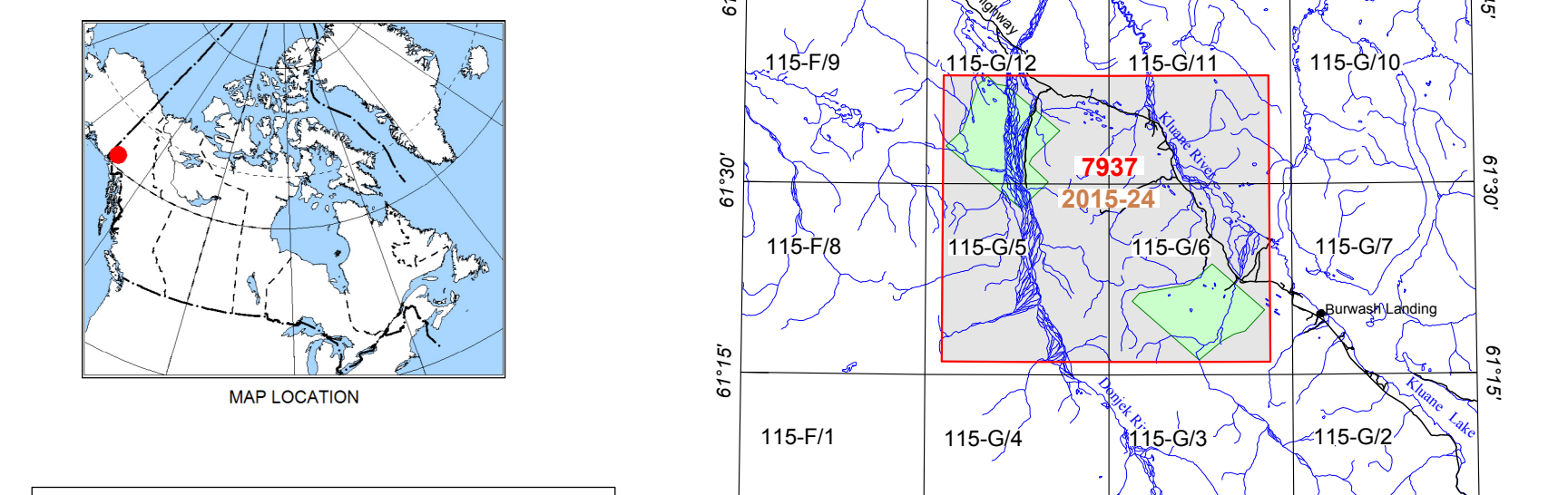
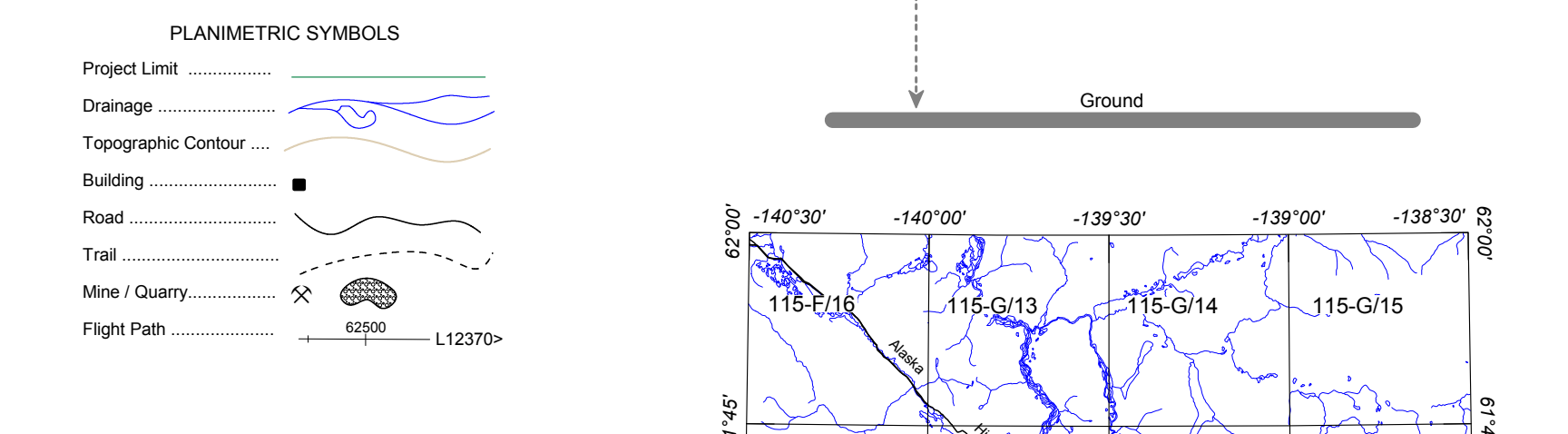
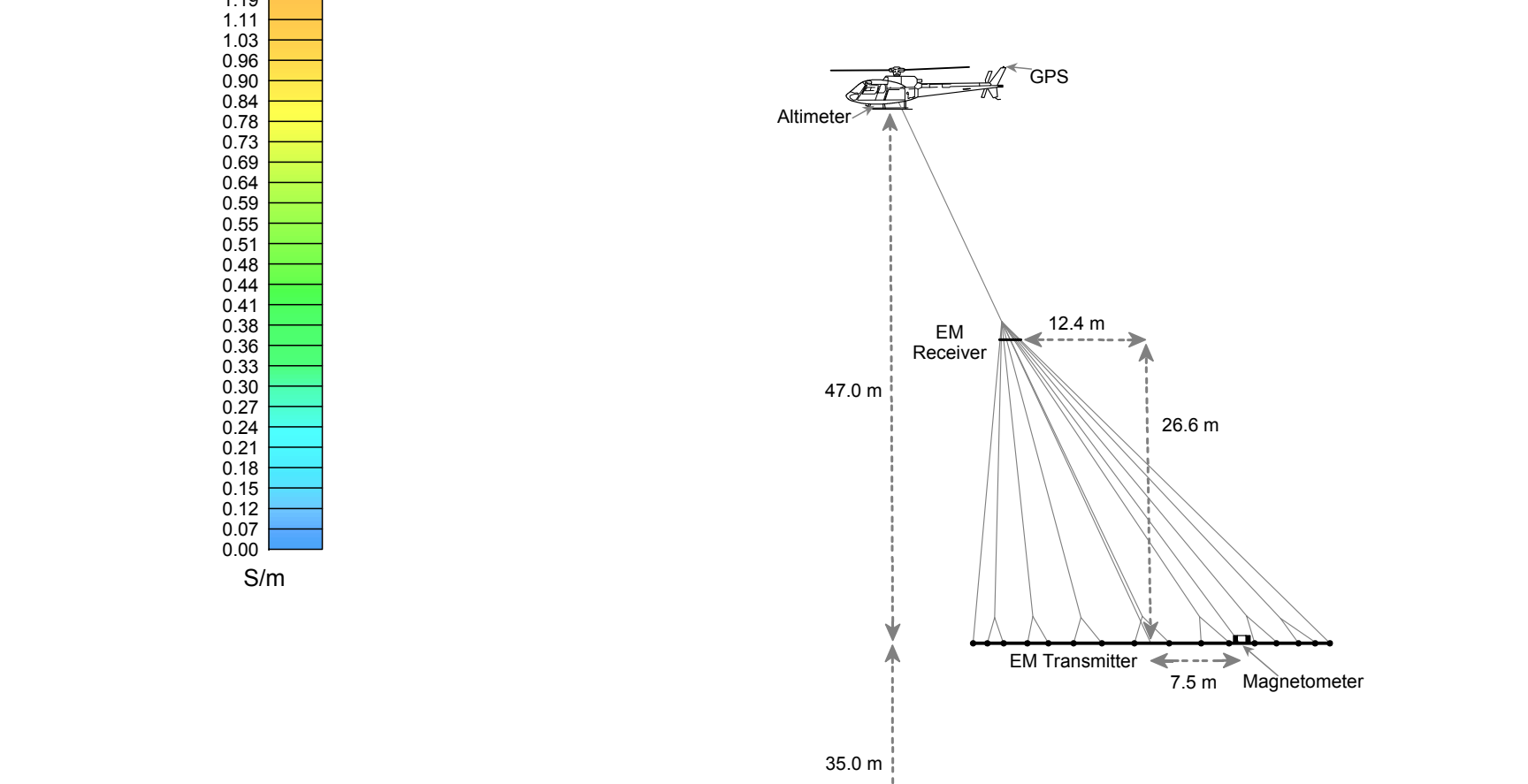
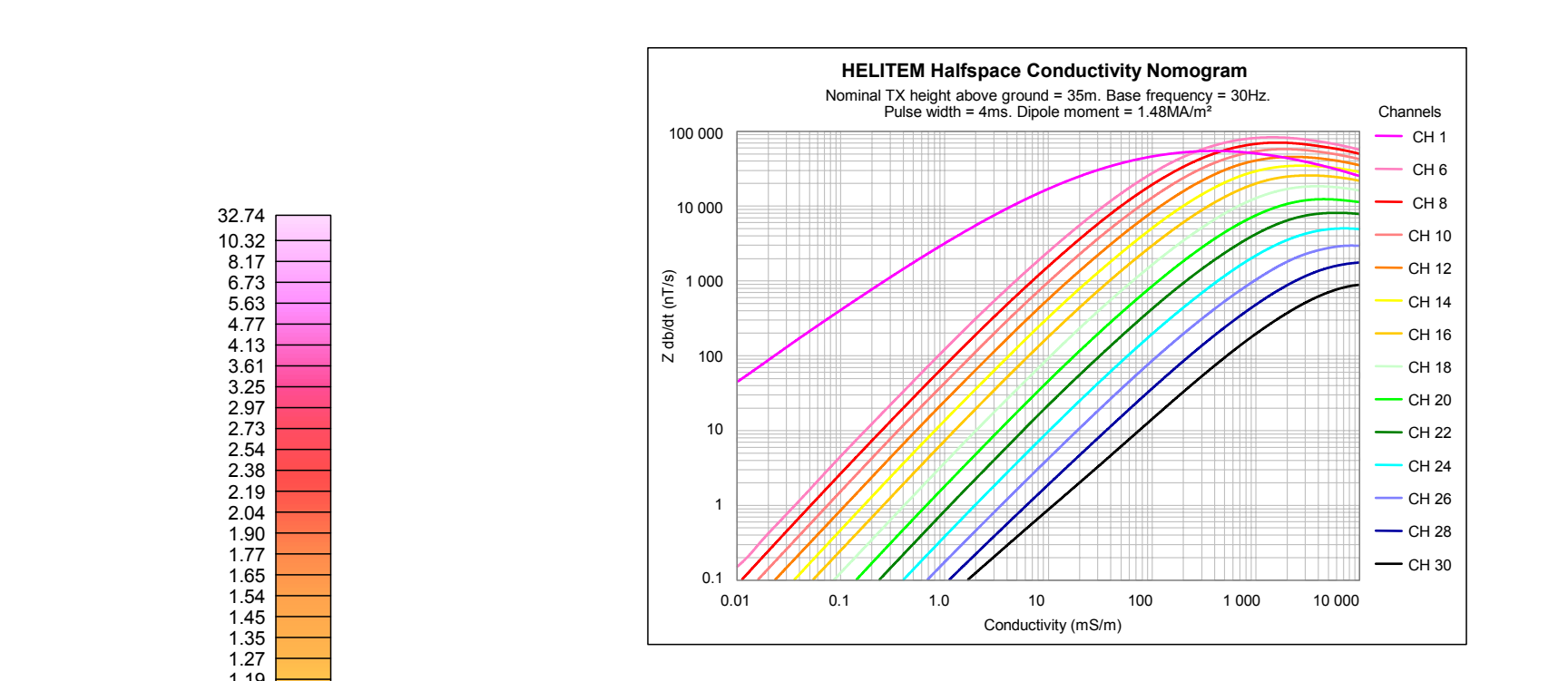
Apparent Conductivity
The apparent conductivity values were derived from selected early, middle and late channels (6, 14 and 22) of the off-time signal, fitted to a homogeneous half-space model. This is performed using a look-up table that contains the response over a range of half-space conductivities and altimeter heights as depicted in the nomogram below.

Electromagnetic Decay Constant
Decay constant (Tau) values are obtained by fitting the data from selected early, middle and late channel ranges (6 to 8, 14 to 17 and 22 to 25) of the off-time signal to a single exponential. The decay constant indicates the relative strength of the conductor. In terms of space, the slope of this function will reflect the exponential decay rate of the transient field and therefore the strength of the conductivity. A slow rate of decay, reflecting a high conductivity, will be represented by a high decay constant value.

Magnetics
The magnetic field was sampled 10 times per second using a cesium vapor magnetometer (sensitivity = 0.005 nT) mounted on the transmitter loop below the aircraft. Differences in magnetic values at the intersection of control and traverse lines were analyzed to obtain a mutually leveled set of magnetic magnetic data. The leveled values were then interpolated to a 62.5 m grid. The International Reference Field (IGRF) defined by a mean GPS altitude (1973.60 m) and a fixed recording rate (60 Hz) is used to remove the diurnal magnetic field variations. The EM receiver magnetic data were recorded ten times per second using a Sorenson CS-2 cesium-vapor magnetometer. The magnetic data were recorded 10 times per second using a Sorenson CS-2 cesium-vapor magnetometer.

The first vertical derivative of the magnetic field is the rate of change of the magnetic field in the vertical direction. Computation of the first vertical derivative removes long-wavelength features of the magnetic field and significantly improves the resolution of closely spaced and successional anomalies. A property of first vertical derivative maps is the coincidence of the zero-value contour with vertical contacts at high magnetic latitudes (Rood, 1965). The first vertical derivative of the magnetic field was calculated by the Fast Fourier Transform on the gridded total magnetic field with a grid cell size of 62.5 m.

References
Hood, P. J., 1965. Gradient measurements in aeromagnetic surveying. Geophysics, v. 30, p. 891-902.



Sheet Titles

- Sheet 1: Time Decay Constant (Tau Z) - Early Channels (5 to 9)
- Sheet 2: Time Decay Constant (Tau Z) - Mid Channels (14 to 17)
- Sheet 3: Time Decay Constant (Tau Z) - Late Channels (22 to 25)
- Sheet 4: Apparent Conductivity - Early Channel (8)
- Sheet 5: Apparent Conductivity - Mid Channel (14)
- Sheet 6: Apparent Conductivity - Late Channel (22)
- Sheet 7: Residual Total Magnetic Field
- Sheet 8: First Vertical Derivative of the Magnetic Field

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GSC OPEN FILE 7937
YGS OPEN FILE 2015-24
KLUANE LAKE WEST ELECTROMAGNETIC SURVEY
PARTS OF NTS 115-G-5, 6, 11 AND 12
APPARENT CONDUCTIVITY
LATE CHANNEL (22)
Scale 1:50 000
NAD 83 / UTM zone 17N

North American Datum 1983
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