

**Technical Information**  
This map was compiled from data acquired during an airborne electromagnetic survey carried out by CGG using a HELITEM™ Time Domain Electromagnetic (TDEM) system. The system was mounted on a Eurocopter AS350B3 helicopter (registration C-FRXX) and was carried out between April 17<sup>th</sup> and April 20<sup>th</sup>, 2015. The aircraft flight elevation was maintained at a nominal ground clearance of 10 m. Aircraft navigation was a 12 channel Novair for dual frequency GPS. Flight height differential correctors were subsequently applied to finalize flight path position. A vertically mounted video camera was used to record images of the ground. The radar height was recorded ten times per second using a Sironix CS-2 cesium-vapor magnetometer.

**Survey Area Parameters:**

Traverse line azimuth	45°/225°
Traverse line spacing	250 m
Tie line azimuth	130°/160°
Tie line spacing	1 000 m
Aircraft nominal clearance	83 m
EM transmitter nominal clearance	35 m
Magnetic sensor nominal clearance	30 m
EM Receiver nominal clearance	63 m

**Electromagnetics**  
The TDEM system operating at a base frequency of 30 Hz transmits a 4 ms time-varying signal from a helicopter. 108 m<sup>2</sup> horizontal loop mounted approximately 47.0 m below and 12.5 m behind the aircraft. This configuration provides a dipole moment of 1.64 x 10<sup>6</sup> Am<sup>2</sup>. The response of conductors in the subsurface is sampled 2048 times per half-cycle (1.4 ms) at 20 m intervals. The EM receiver is a vertically oriented stack of 12 m diameter coils with a total height of 12.5 m. The EM system records data in a continuous stream for each of the three components. A 3-second tapered stack was used before outputting the data as 30 times windows at a rate of 10 samples per second. The EM receiver measures the change in the magnetic field with respect to the IGRF from which the secondary total magnetic field (B) is numerically integrated. High-altitude background sections taken at the start and end of each flight allow a 1st-order removal of system drift.

**Electromagnetic System Specifications**

Base Frequency	30 Hz
Waveform	Half-sine wave
Pulse width	4 ms
Transmitter Area	700 m <sup>2</sup> (2 turns)
Transmitter Off-time	125 ms
Transmitter Loop	30 m diameter
Transmitter Current	1300 A
Loop moment (approximate)	1.64 x 10 <sup>6</sup> Am <sup>2</sup> (B-T-C)
Windowed data sampling rate	10 Hz
Receiver	Scorpion induction coil (X, Y, Z)
Transducer Response	Voltage (dBV)
Digital recording	All raw data channels (30 channels)
1 <sup>st</sup> off-time channel	Channel 6 at ~1.69 ms after pulse turn on
Tx-Rx Configuration	Towed transmitter below towed receiver

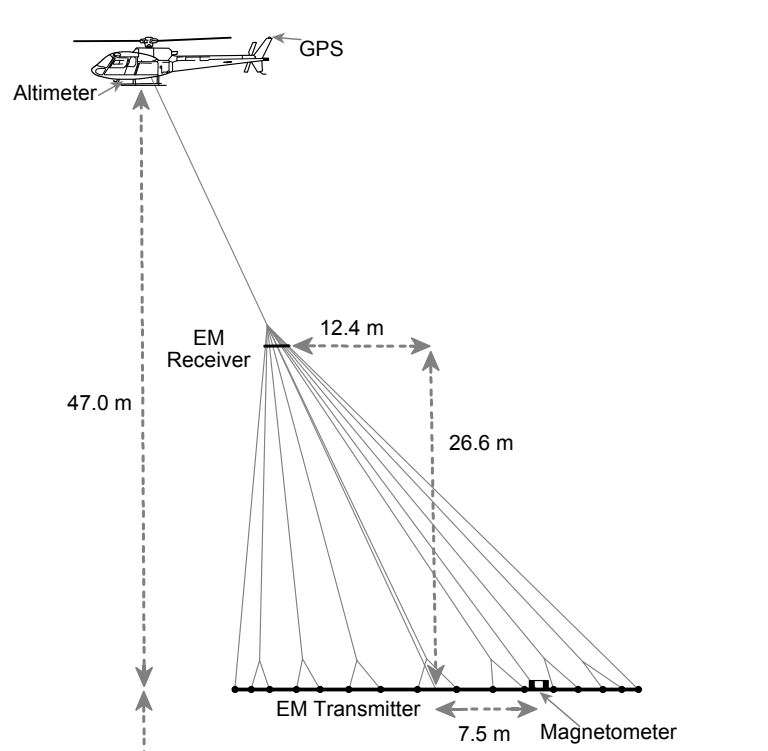
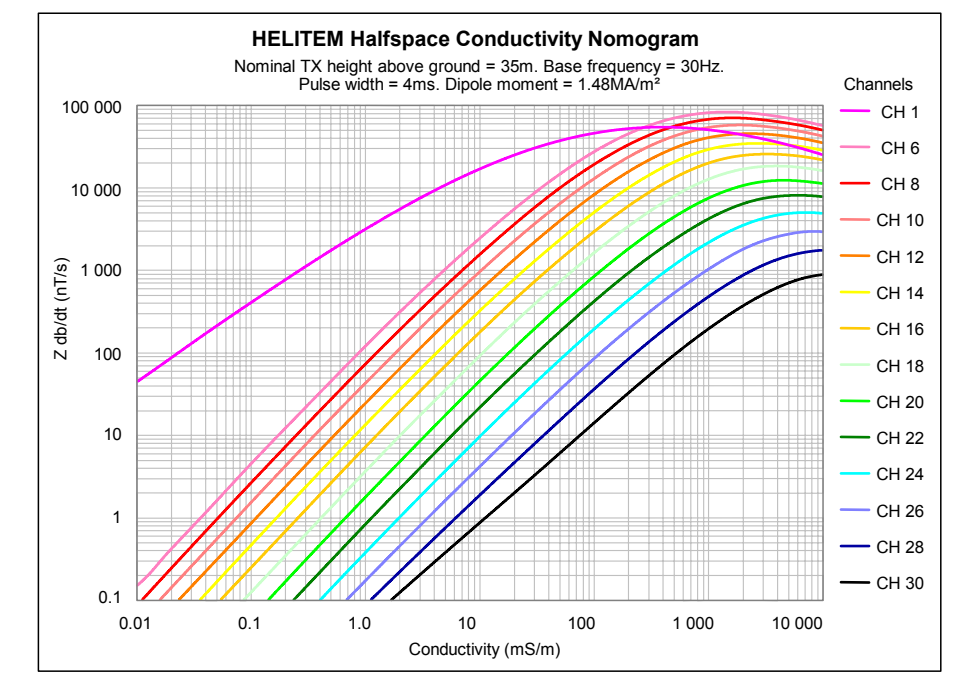
**Apparent Conductivity**  
The apparent conductivity values were derived from selected early, middle and late channels (6, 14 and 22) of the off-time signal, fitted to a homogeneous half-space model. This is performed using a look-up table that contains the response over a range of half-space conductivities and altimeter heights as depicted in the nomogram below.

**Electromagnetic Decay Constant**  
Decay constant (TAU) values are obtained by fitting the data from selected early, middle and late channels (6 to 6, 14 to 17 and 22 to 25) of the off-time signal to a single exponential. The decay constant indicates the relative strength of the conductor. In an early channel, the slope of the function will reflect the exponential decay rate of the transient field and therefore the strength of the conductivity. A slow rate of decay, reflecting a high conductivity, will be represented by a high decay constant value.

**Magnetic**  
The magnetic field was sampled 10 times per second using a split-beam cesium vapor magnetometer (sensitivity = 0.005 nT) mounted on the transmitter loop towed below the aircraft. Differences in magnetic values at the intersection of control and traverse lines were analyzed to obtain a mean 12.5 m wide set of flight-line magnetic data. The leveled values were then interpolated to a 62.5 m grid. The International Geomagnetic Reference Field (IGRF) defined at a mean GPS altitude (1073.6 m) for a constant recording date (April 20, 2015) was then removed. Removal of the IGRF, representing the magnetic field of Earth's core, produces a residual component related essentially to magnetizations within Earth's crust.

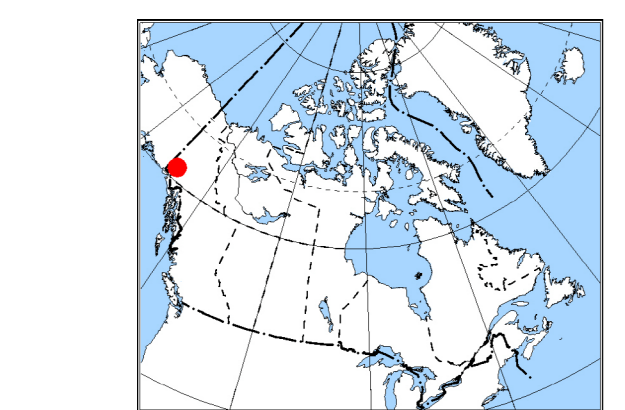
The first vertical derivative of the magnetic field is the rate of change of the magnetic field in the vertical direction. Computation of the first vertical derivative removes long-wavelength features of the magnetic field and significantly improves the resolution of closely spaced and unsegmented anomalies. A property of first vertical derivative maps is the coincidence of the zero-value contour with vertical contacts at high magnetic latitudes (Koch, 1965). The first vertical derivative of the magnetic field was calculated by fast Fourier transform on the gridded total magnetic field with a grid cell size of 62.5 m.

**References**  
Hood, P.J., 1965. Gradient measurements in aeromagnetic surveying. Geophysics, v. 30, p. 891-902.



**PLANIMETRIC SYMBOLS**

- Project Limit
- Drainage
- Topographic Contour
- Road
- Tail
- Mine/Quarry
- Flight Path



**Sheet Titles**

- Sheet 1: Time Decay Constant (TAU-Z) - Early Channels (6 to 9)
- Sheet 2: Time Decay Constant (TAU-Z) - Mid Channels (14 to 17)
- Sheet 3: Time Decay Constant (TAU-Z) - Late Channels (22 to 25)
- Sheet 4: Apparent Conductivity - Early Channel (6)
- Sheet 5: Apparent Conductivity - Late Channel (22)
- Sheet 6: Residual Total Magnetic Field
- Sheet 7: First Vertical Derivative of the Magnetic Field

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**KLUANE LAKE WEST ELECTROMAGNETIC SURVEY**  
YUKON

Parts of NTS 115-G/5, 6, 11 and 12

**TIME DECAY CONSTANT (TAU-Z) EARLY CHANNELS (6 TO 9)**

Scale 1:50 000

North American Datum 1983  
GCS NAD 83 / UTM zone 7N

Open File 7937  
Commission Geographique du Canada  
2015

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